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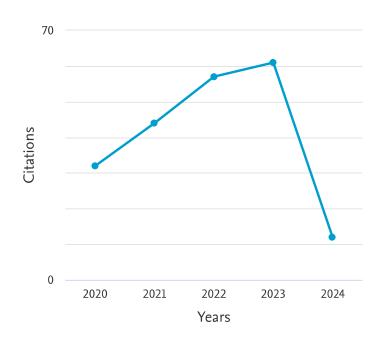
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	Documents	Citations	<2020	2020	2021	2022	2023	2024	Subtotal	>2024	Total
		Total	283	32	44	57	61	12	206	0	489
1	Digital Twin Based a Processing Technology Assisted by a MCP	2023							0		0
2	Flexible Manufacturing with Integrated Robotic Systems in th	2023							0		0
3	Modeling and Control an A/DT Served by an ACPS based on SCAD	2023							0		0
4	Digital Twin for a Multifunctional Technology of Flexible As	2022					12	2	14		14

	Documents	Citations	<2020	2020	2021	2022	2023	2024	Subtotal	>2024	Total
		Total	L 283	32	44	57	61	12	206	0	489
5	Mobile Visual Servoing Based Control of a Complex Autonomous	2022				1	2		3		3
6	Communication and Control of an Assembly, Disassembly and Re	2022				1	4	2	7		7
7	Event-based PID control in a flexible manufacturing process	2022					1		1		1
8	Complex Autonomous System Assisting a Manufacturing Technolo	2022							0		0
9	Digital Twin for a Mechatronics Line with Integrated Mobile	2022							0		0
<u> </u>	Thermally activated al(Oh) ₃ part ii—effect of dif	2021				2	4	1	7		7
11	Thermally activated al(Oh) ₃ : Part i—morphology an	2021				4			4		4
<u> </u>	Multifunctional technology of flexible manufacturing on a me	2021				7	3	1	11		11
<u> </u>	CAS and IRM Integrated into a Multifunctional Flexible Manuf	2021							0		0
<u> </u>	Manufacturing technology on a mechatronics line assisted by	2020			5	6	3		14		14
<u> </u>	Improved Image Processing Algorithm for Quality Test on a Fl	2020				1			1		1
<u> </u>	Optimal Control of Automated Resupply on a Flexible Manufact	2020					1		1		1
<u> </u>	Mechatronics Manufacturing Line with Integrated Autonomous R	2019		1	2	2	2		7		7
<u> </u>	Optimal control of the complete assembly/disassembly cycle f	2019		2	1	1	2		6		6
<u> </u>	Trajectory tracking nonlinear control and narrow spaces navi	2018							0		0
20	Visual servoing systems based control of complex autonomous	2018	2	1	2	2			5		7
21	Extended approach for modelling and simulation of mechatroni	2018	2	1	1	1			3		5
22	Hybrid modelling and simulation of a P/RML with integrated c	2018	1	1		1	1		3		4
23	Trajectory-Tracking Sliding-Mode Control of the Autonomous W	2018		1					1		1
<u> </u>	SHPN models based simulation and control of mobile robotic s	2017	2						0		2

Documents	Citations	<2020	2020	2021	2022	2023	2024	Subtotal	>2024	Total
	Tota	al 283	32	44	57	61	12	206	0	489
SHPN modelling, visual servoing and control of WMR with RM i	2017							0		0
Visual servoing and obstacle avoidance method based control	2017		1					1		1
Hybrid modeling, balancing and control of a mechatronics lin	2016	2				1		1		3
Control and obstacle avoidance of a WMR, based on sliding-mo	2016		1	3	4			8		8
Cycle time optimization of a reversible A/DML served by a mo	2015	1	1	1		1		3		4
Sliding-mode control and sonnar based bubble rebound obstacl	2015	1						0		1
Modelling and control of an assembly/disassembly mechatronic	2014	11	6	3	5	7	2	23		34
Hybrid modelling based control of an processing/reprocessing	2013	2	1	1	2			4		6
A theoretical approach of the generalized hybrid model based	2013	1						0		1
Hybrid model based control of a mechatronics line served by	2013	2						0		2
Discrete modelling based control of a processing/reprocessin	2013	1						0		1
New approach in control of assembly/disassembly line served	2012	9	2	1				3		12
Control of automatic robot with guided manipulator integrate	2012	3						0		3
Hybrid system control of an assembly/disassembly mechatronic	2012	10	1					1		11
3D fit garment simulation based on 3D body scanner anthropom	2012	2						0		2
Two approaches in modeling of assembly/disassembly line with	2012	1		1			1	2		3
Task planning algorithm in hybrid assembly/disassembly proce	2012	16	2	1	2	1	2	8		24
Backstepping control of wheeled mobile robots	2011	7	3	2	2	1		8		15
Adaptive disassembly sequence control by using mobile robots	2011	14		2		1		3		17
Discrete-time sliding-mode control of a mobile platform with	2011	1		1				1		2
	SHPN modelling, visual servoing and control of WMR with RM i Visual servoing and obstacle avoidance method based control Hybrid modeling, balancing and control of a mechatronics lin Control and obstacle avoidance of a WMR, based on sliding-mo Cycle time optimization of a reversible A/DML served by a mo Sliding-mode control and sonnar based bubble rebound obstacl Modelling and control of an assembly/disassembly mechatronic Hybrid modelling based control of an processing/reprocessing A theoretical approach of the generalized hybrid model based Hybrid model based control of a mechatronics line served by Discrete modelling based control of a processing/reprocessin New approach in control of assembly/disassembly line served Control of automatic robot with guided manipulator integrate Hybrid system control of an assembly/disassembly mechatronic 3D fit garment simulation based on 3D body scanner anthropom Two approaches in modeling of assembly/disassembly line with Task planning algorithm in hybrid assembly/disassembly proce Backstepping control of wheeled mobile robots Adaptive disassembly sequence control by using mobile robots	SHPN modelling, visual servoing and control of WMR with RM i SHPN modelling, visual servoing and control of WMR with RM i Visual servoing and obstacle avoidance method based control Hybrid modeling, balancing and control of a mechatronics lin Control and obstacle avoidance of a WMR, based on sliding-mo Cycle time optimization of a reversible A/DML served by a mo Sliding-mode control and sonnar based bubble rebound obstacl Modelling and control of an assembly/disassembly mechatronic Hybrid modelling based control of an processing/reprocessing A theoretical approach of the generalized hybrid model based Hybrid model based control of a mechatronics line served by Discrete modelling based control of a processing/reprocessin New approach in control of assembly/disassembly line served Control of automatic robot with guided manipulator integrate Hybrid 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2013 1 1 6 3 Hybrid modelling based control of an assembly/disassembly mechatronic 2013 2 1 1 6 3 Hybrid model based control of an enchatronics line served by 2013 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 <td>SHPN modelling, visual servoing and control of WMR with RM i 2017 283 32 44 57 Visual servoing and obstacle avoidance method based control 2017 </td> <td>SHPN modelling, visual servoing and control of WMR with RM i 2017 283 32 44 57 61 Wisual servoing and obstacle avoidance method based control 2017 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1</td> <td>SHPN modelling, visual servoing and control of WMR with RM i 2017 Wisual servoing and obstacle avoidance method based control 2017 Hybrid modelling, balancing and control of a mechatronics lin 2016 Control and obstacle avoidance of a WMR, based on sliding-mo 2016 Cycle time optimization of a reversible A/DML served by a mo 2015 Sliding-mode control of an assembly/disassembly mechatronic 2016 Modelling and control of an assembly/disassembly mechatronic 2018 A theoretical approach of the generalized hybrid model based 2013 Hybrid modelling based control of an processing/reprocessing 2013 A theoretical approach of the generalized hybrid model based 2013 Hybrid model based control of a mechatronics line served by 2013 Posser processing/reprocessing 2013 Posser processing/reprocessing/reprocessing 2013 Posser processing/reprocessing 2013</td> <td>SHPN modelling, visual servoing and control of WMR with RM i 2017 USB 10 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1</td> <td> Total 283 32 44 57 61 12 206 90 12 13 14 15 15 15 15 15 15 15</td>	SHPN modelling, visual servoing and control of WMR with RM i 2017 283 32 44 57 Visual servoing and obstacle avoidance method based control 2017	SHPN modelling, visual servoing and control of WMR with RM i 2017 283 32 44 57 61 Wisual 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	Documents	Citations	<2020	2020	2021	2022	2023	2024	Subtotal	>2024	Total
		Tota	l 283	32	44	57	61	12	206	0	489
45	Discrete-time sliding-mode control of four driving-steering	2011	1						0		1
46	Discrete-time sliding-mode control of four driving/steering	2011	1				1		1		2
47	Discrete-time sliding mode control of wheeled mobile robots	2011	14			2	1		3		17
48	Trajectory-tracking and discrete-time sliding-mode control o	2011	16	1	6	1	7		15		31
49	Fuzzy control and bubble rebound obstacle avoidance of a mob	2010	2						0		2
<u> </u>	Lateral motion control of four-wheels steering vehicle using	2010	9	2	1		1		4		13
<u> </u>	Formation control of multi-robots via sliding-mode technique	2010							0		0
<u> </u>	Sliding-mode controller for four-wheel-steering vehicle: Tra	2010	12		1				1		13
<u> </u>	The bubble rebound obstacle avoidance algorithm for mobile r	2010	10		2	2	1		5		15
<u> </u>	Sliding-mode trajectory-tracking control for a four-wheel-st	2010	16		2				2		18
<u> </u>	Obstacle avoidance and path following control of a WMR used	2010							0		0
<u> </u>	Control of mobile platforms as robotic assistants for elderl	2009	3						0		3
<u> </u>	Sliding-mode control for trajectory-tracking of a wheeled mo	2009	47	3	5	4	2	1	15		62
<u> </u>	Wheeled mobile robot control using virtual pheromones and ne	2009	3						0		3
<u> </u>	Distributed system of mobile platform obstacle avoidance and	2009	4						0		4
60	Virtual pheromones and neural networks based wheeled mobile	2009	3	1					1		4
<u> </u>	Virtual pheromones to control mobile robots. A neural networ	2009	4			1			1		5
62	Sliding-mode real-time mobile platform control in the presen	2009	11			1			1		12
63	Path following, real-time, embedded fuzzy control of a mobil	2008	11				1		1		12
64	On-line parameter estimation and adaptive gain smooth slidin	2007	1						0		1

	Documents	Citations	<2020	2020	2021	2022	2023	2024	Subtotal	>2024	Total
		Total	283	32	44	57	61	12	206	0	489
65	Robots control based on parameter identification and adaptiv	2005	2						0		2
66	Discrete-time sliding-mode WMR control based on parameter id	2005	3						0		3
67	Smooth variable structure observer controller with adaptive	2003	2						0		2
68	Adaptive Gain Sliding Observer Based Sliding Controller for	2003	17			2			2		19
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